$\frac{\text{CS 6640: Introduction to Image Processing}}{\text{Fall 2013}}$ Test 1 — Takehome — Due 11/18/2013

**Rules:** 

- Closed book.
- One page of notes (front and back).
- No calculators.

## Hints:

- The term "describe" does not mean complete sentences and paragraphs or essays. If it's easier you may use simple bullets and meaningful phrases to answer such questions.
- If you split answers across pages (or on the backs of pages) make a clear note on the page where the question is posed to indicate you have done so. Clearly note the question number (and part) on the separate page.
- There are **six** questions for a total of 100 points. Point values are roughly correlated with the amount of time you should devote to each question.

- 1. **[15 pts.]** Suppose we have correspondences  $(x_1, y_1), (x_2, y_2), \ldots, (x_N, y_N)$  in one image, and  $(x'_1, y'_1), (x'_2, y'_2), \ldots, (x'_N, y'_N)$  in another.
  - (a) We wish to find a simple translation  $(t_x, t_y)$ , and we wish to overconstrain the system. What penalty function would we minimize (to get a good answer) and what linear system would we use to solve the problem? Give the equations/matrices.
  - (b) If we wish to find both a translation and an isotropic scaling of one of the images, what linear system would we use? Give equations/matrices.
  - (c) Suppose we wish to find the angle of rotation between two images that best describes these correspondences. Show that the problem is no longer linear. Give the equation (hint: summation) for the penalty function in terms of the unknowns and describe (briefly) one strategy for finding the best rotation.

2. **[25 pts.]** This question deals with the topic of *bilateral filtering*. The general form of bilateral filter is

$$f_i \leftarrow k_i^{-1} \sum_{j \in N} f_j G(\bar{x}_i - \bar{x}_j) H(f_i - f_j)$$

where N is the set of pixels in the neighborhood,  $\bar{x}_i$  and  $\bar{x}_j$  are pixel locations for the pixel being updated and those pixels in the neighborhood (respectively), and

$$k_i = \sum_{j \in N} G(\bar{x}_i - \bar{x}_j) H(f_i - f_j),$$

is a normalization factor for each pixel i in the image.

- (a) Write a pseudocode implementation of the bilateral filter that runs over the whole image for a specified  $M \times M$  window size.
- (b) What are typical choices of G and why?
- (c) What are typical choices of H and why?
- (d) There are typically two parameters in this filter, one that controls the shape of G (call it  $\alpha$ ) and one that controls the shape of H (call it  $\beta$ ). What aspect of the filter do each of these parameters affect and how (briefly) should they be chosen?
- (e) What is the purpose of including the normalization  $k_i$  in the filter? What artifacts could occur if you were to exclude this division by  $k_i$ ?

## 3. **[20 pts]**

(a) Prove that

$$\operatorname{sinc}(\mathbf{x}) \otimes \operatorname{sinc}(\mathbf{x}) = \operatorname{sinc}(\mathbf{x})$$

(b) Prove that for any signal that is band limited to have only nonzero energy below frequency  $s_0$ , that  $2s_0 \operatorname{sinc}(2s_0 \mathbf{x})$  is the identity operator for convolution.

- 4. **[15 pts.]** Give a continuous Fourier transforms for the following. It is recommended that you use identities where ever possible, rather than derive them from scratch.
  - (a)  $f(x) = \begin{cases} \frac{1}{2} (\cos(\pi x) + 1.0) & -1 \le x \le 1 \\ 0 & \text{otherwise} \end{cases}$ (b)  $\cos(\omega x) e^{-\frac{-x^2}{2\sigma^2}}$ (c)

$$\cos(ax)\sin(bx)$$

## 5. **[15 pts.]**

(a) Find and plot the Fourier transform of

$$f(t) = \cos(4\pi t)\cos(6\pi t)$$

Hint: you may use the convolution theorem.

(b) If we were to sample f(t), what would be the largest sampling interval  $(\Delta T)$  that still avoids aliasing?