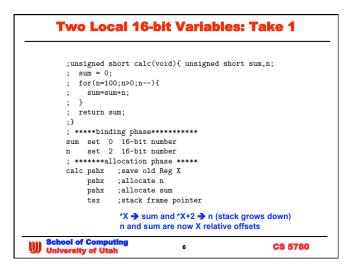


# \*\*Description of Computing University of Utah \*\*Description of



```
Take 1 continued
                ; *******access phase ******
                     ldd #0
                     std sum,x ;sum=0
                     ldd #100
                     std n.x
                                 :n=100
                loop ldd n,x
                                 ;RegD=n
                     addd sum,x ;RegD=sum+n
                     std sum,x ;sum=sum+n
                    ldd n,x
                                 ;n=n-1
                     subd #1
                     std n,x
                    bne loop
                ; ******deallocation phase ***
ldd sum,x ;RegD=sum
                                 ;deallocate sum
                     pulx
                     pulx
                                 ;deallocate n
                     pulx
                                 ;restore old X
                     rts
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                                    7
```

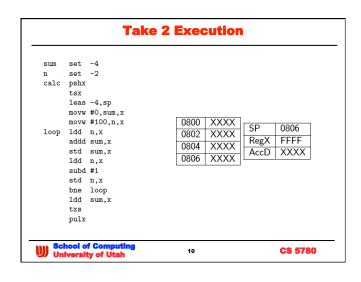
```
Two Local 16-bit Variables: Take 2

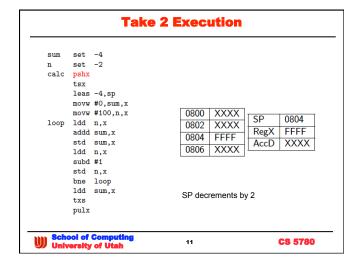
• 6812 allows negative offset addressing

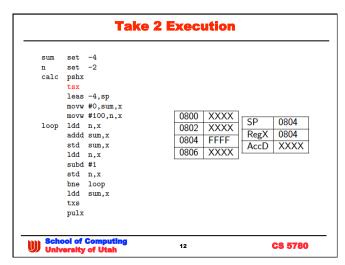
; *****binding phase**********
sum set -4 16-bit number
n set -2 16-bit number
; *******allocation phase ******
calc pshx ; save old Reg X
tsx ; stack frame pointer
leas -4,sp ; allocate n,sum

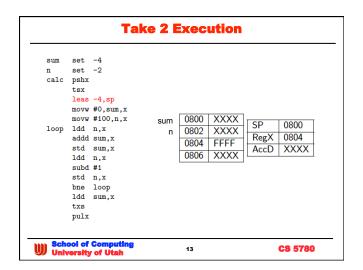
X now points inside the stack frame
leas: load effective address → SP
```

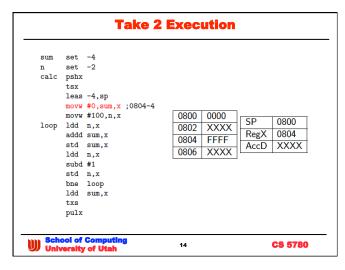
```
Take 2 continued
  ; *******access phase *******
      movw #0,sum,x ;sum=0
      movw #100,n,x ;n=100
 loop ldd n,x ;RegD=n
      addd sum,x ;RegD=sum+n
      std sum,x ;sum=sum+n
      ldd n,x
                  ;n=n-1
      subd #1
      std n,x
      bne loop
  ; *****deallocation phase *****
      ldd sum,x ;RegD=sum
                                        deallocation phase now 1
                   ;deallocation
       txs
                                        instruction shorter than in
      pulx
                   ;restore old X
                                        Take 1
      rts
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```

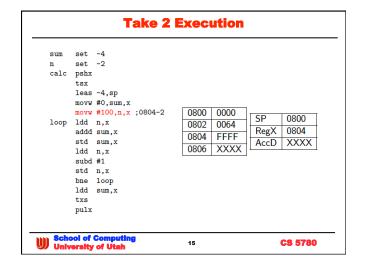


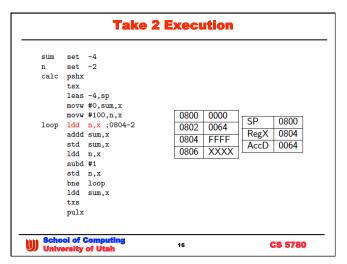


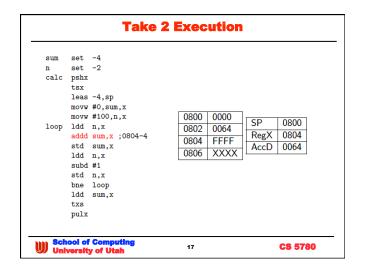


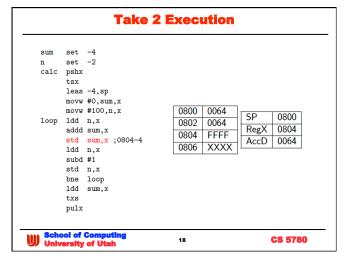


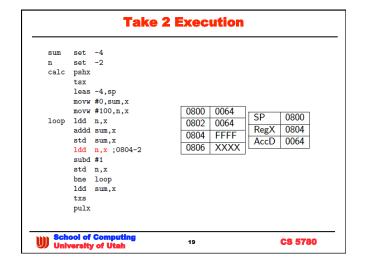


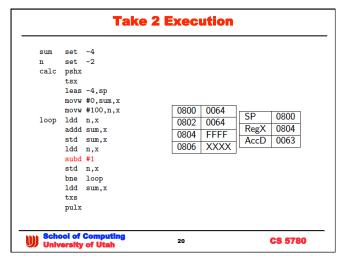


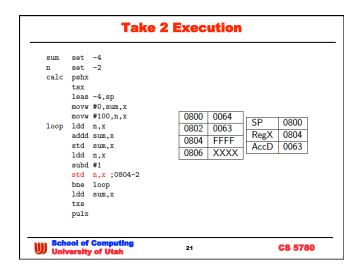


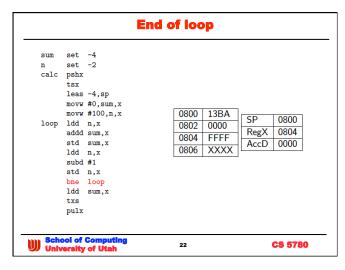


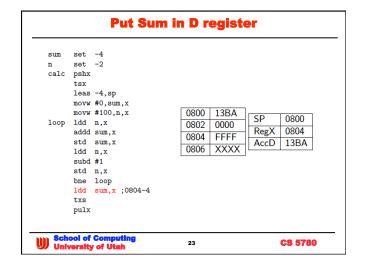


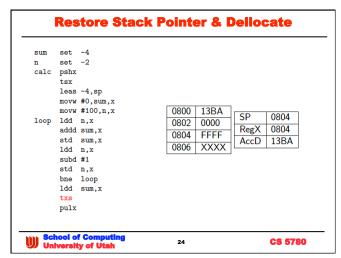


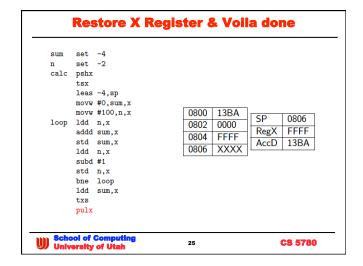


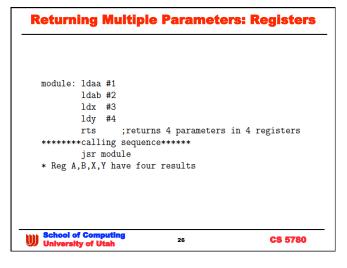




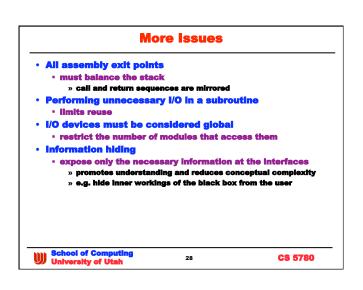








# **Returning Multiple Values: stack** equ 2 data1 data2 equ 3 module: movb #1,data1,sp ;1st parameter onto stack movb #2,data2,sp ;2nd parameter onto stack rts \*\*\*\*\*\*calling sequence\*\*\*\*\* leas -2,sp ;allocate space for results jsr module pula ;1st parameter from stack staa first pula ;2nd parameter from stack staa second School of Computing University of Utah CS 5780 27



# **Module Decomposition**

- Coupling
  - Influence a module's behavior has on another module
- Task decomposition goals
  - · make the SW organization easier to understand
  - Increase the number of modules
    - » this may increase code footprint and/or increase run time · due to extra subroutine linkages
    - » but start properly and then optimize if you have to
  - » minimize coupling as much as possible
- Develop, connect and test modules in a hierarchy
  - top-down "write no software until every detail is specified"
  - bottom-up "one brick at a time"
- · Initial design is best done top-down
- Implementation is best done bottom-up
- · namely you have something to test
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# **Layered Software Systems**

- - SW continually changes as better HW or algorithms become
- · Layered SW facilitates these changes
  - top layer is the main program
  - lowest layer is the HW abstraction layer
     modules that access the I/O HW
- Hierarchy should be strict
  - each layer can only call lower layers
     » Ideal is to only call the next lower layer

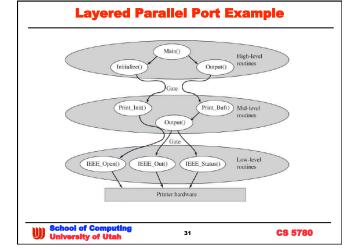
  - - » defines the interface at the next lower layer

  - If this happens

    » each layer can be replaced without affecting other layers
- ble downside: code bloat ptimize last policy is a good one asier to optimize correctly b

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# **Layered SW Rules**

- Modules may make calls to modules in the same layer
- Modules may call lower layer only using gate
- Module has no access to any function or variable in another layer
  - · except via gate
- · Modules can't call upper layers
- Ideal yet optional
  - · module calls only next layer down
  - · all I/O access is at the lowest layer
  - · user interface is at the highest level

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## **Device Driver Concepts**

- Purpose
  - SW interface to physical I/O devices
    - » Interface API for upper layers
  - » low-level routines to configure and perform actual I/O
- Separation of policy and mechanism is important
  - e.g. Interface may include routines to open, read, and write files
    - » but it shouldn't care about what device the files reside on
- · HAL
  - provide a good hardware abstraction layer



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#### **Low-Level Device Drivers**

- Normally found in BIOS ROM
  - basic I/O system
- Good low-level drivers allow:
  - new hardware to be installed
  - new algorithms to be implemented
    - » synchronization w/ completion flags/interrupts
  - » error detection and recovery methods
  - higher-level features built on top of low-level » OS features like blocking semaphores
    - » driver features like automatic compression/decompression



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# **Encapsulated Objects in ANSI C**

- · Choose names to reflect the module in which they are defined

In C: LCD\_Clear() In C++: LCD.clear()

Only put public function declarations in header files.

Example (Timer.H):

void Timer\_Init(void);

void Timer\_Wait10ms(unsigned short delay);

Since the function wait(unsigned short cycles) is not in the header file, it is a private function.

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#### Reentrancy

- Reentrant if
  - · It can be conurrently executed by 2 or more threads
  - or by main and one or more interrupts
- **Rules for reentrant functions** 
  - · must not call a non-reentrant function
  - · must not touch global variables w/o proper locking

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# **Coding Guidelines**

- Guidelines that cannot be checked by a smart compiler are less effective
- Too many guidelines are worthless
  - too hard to remember or enforce
- Following is a 10 rule list
  - by Gerard Holzman
    - » leads NASA/JPL's Lab for Reliable Software
    - · needless to say it's hard to debug things in outer space
  - note
    - » these are good things to know
    - » even though some of the implied tools aren't available to you at the moment

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#### Rule 1

Rule: Restrict all code to very simple control flow constructs – do not use *goto* statements, *setjmp* or *longjmp* constructs, and direct or indirect *recursion*.

Simple control translates into easier code verification and often improved clarity.

Without recursion the function call graph is acyclic which directly aids in proving boundedness of the code.

This rule doesn't require a single return point for a function although this often simplifies control flow.

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# Rule 2

Rule: All loops must have a fixed upper-bound. It must be trivially possible for a checking tool to *prove* statically that a preset upper-bound on the number of iterations of a loop cannot be exceeded. If the loop-bound cannot be proven statically, the rule is considered violated.

The absence of recursion and presence of loop bounds prevents runawway code.

Functions intended to be nonterminating must be proved to

Some functions don't have an obvious upper bound (i.e. traversing a linked list), so an artificial bound should be set and checked via an assert.

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#### Rule 3

Rule: Do not use dynamic memory allocation after initialization.

Memory allocation code is unpredictable from a time standpoint and therefore impractical for time critical code.

Many errors are introduced by improper dynamic memory allocation.

Without dynamic memory allocation the stack is used for dynamic structures and without recursion bounds can be proved on stack size.

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## Rule 4

Rule: No function should be longer than what can be printed on a single sheet of paper in a standard reference format with one line per statement and one line per declaration. Typically, this means no more than 60 lines of code per function.

Long functions are like run-on sentences: they need to be rewritten.

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#### Rule 5

Rule: The assertion density should average to a minimum of two assertions per function. Assertions are used to check for anomalous conditions that should never happen in real-life executions. Assertions must always be side-effect free and should be defined as Boolean tests. When an assertion fails, an explicit recovery action must be taken.

Use of assertions is recommended as part of a strong defensive coding strategy.

Assertions can be used to check pre- and post-conditions of functions, parameter values, return values, and loop invariants.

Assertions can be disabled in performance critical code because they are side-effect free.

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# Rule 6

*Rule:* Data objects must be declared at the smallest possible level of scope.

Variable will not be modified in unexpected places if they are not in scope.

It can be easier to debug a problem if the scope of the variable is smaller.

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# Rule 7

Rule: The return value of non-void functions must be checked by each calling function, and the validity of parameters must be checked in each function.

If the response to the error would be no different to the response to the success then there is no point in checking the value.

Useless checks can be indicated by casting the return value to (void).

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#### Rule 8

Rule: The use of the preprocessor must be limited to the inclusion of header files and simple macro definitions. Token pasting, variable argument lists, and recursive macro calls are not allowed. All macros must expand into complete syntactic units. The use of conditional compilation directives is often also dubious but cannot always be avoided. Each use of a conditional compilation directive should be flagged by a tool-based checker and justified in the code.

Conditional compilation directives can result in an exponentially growing number of code versions.

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#### Rule 9

Rule: The use of pointers should be restricted. Specifically, no more than one level of dereferencing is allowed. Pointer dereference operations may not be hidden in macro definitions or inside typedef declarations. Function pointers are not permitted.

Pointers are easily misused even by experienced programmers. Function pointers can severely limit the utility of static code checkers.

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# Rule 10

Rule: All code must be compiled, from the first day of development, with all compiler warnings enabled at the compiler's most pedantic setting. All code must compile with these settings without any warnings. All code must be checked daily with at least one, but preferably more than one, state-of-the-art static code analyzer and should pass the analyses with zero warnings.

This rule should be followed even in the case when the warning is invalid.

Code that confuses the compiler or checker enough to result in an invalid warning should be rewritten for clarity.

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Static checkers should be required for any serious coding project.

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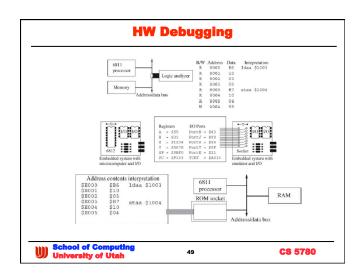
## **Debugging Theory**

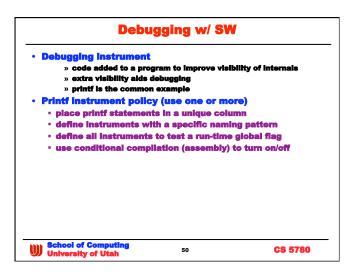
- Process of testing, stabilizing, localizing, and correcting errors
- Research in program monitoring & debugging has not kept up
  - gdb has been around for 30+ years
  - · so has printf
  - alas the Symbolics 3600 system has been left behind

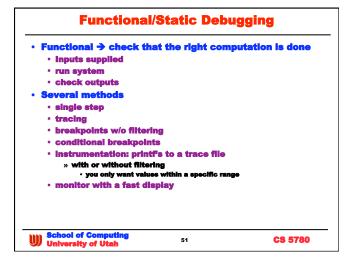
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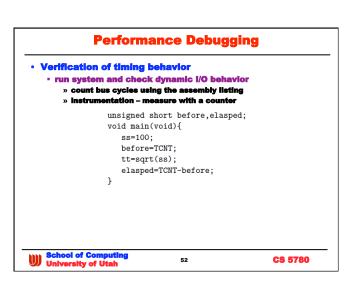
- » it shouldn't have
- ES debugging is even more complicated
  - by concurrency and real-time requirements
  - · printf is a problem because they are slow

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# **Instrumentation via Output Port**

```
Set bset PORTB, #$40
Clr bclr PORTB, #$40
   rts
loop jsr Set
   jsr Calculate ; function under test
    jsr Clr
    bra loop
```

How would you improve on this?

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# **Concluding Remarks**

- · As Arlo says
  - "you can't always do what you're supposed to do"
- But
  - keeping these coding tips in mind will make you a better programmer
  - and reduce hair pulling panic attacks
  - · In later professional life
    - » these types of things will be mandated by your company

       albeit in a slightly different form
- - might as well develop good habits early
     » some of you already have

