

Introduction to Embedded Systems

CS/ECE 6780/5780

AI Davis

Today's topics:

- some logistics updates
- ubiquitous diversity of embedded systems
- note – figures obviously copied & w/out credits come from the book

Logistic Changes

- **Lab sections**
 - 1: Wed 1200 – 1500 (William)
 - 2: Wed 1500 – 1800 (Torrey)
 - 3: Fri 0900 – 1200 (Torrey)
 - 4: Fri 1200 – 1500 (William)
- **Mailing lists now work**
 - deadline to sign up stays the same 2359 tomorrow
 - » “git r’ done”
 - start using the mailing list after that to find a team mate if needed
- **Next week**
 - teams formed, lab sections designated & lab kits checked out
 - lab 1 will be handed out
- **Week after next**
 - labs start
- **Revised schedule on the website**
 - previous optimistic schedule was clearly bogus

What is an Embedded System?

- **Wide variety of interpretations**
 - **special-purpose computer controlled gizmo**
 - » you see the gizmo but not the computer
 - » computer is hidden & not programmed by the user
 - some user configuration is possible
 - but real programming was done by a system specific developer
 - **anything that isn't a PC or a server?**
 - » reasonable view
 - » note PC's and particularly servers contain ES's
 - thermal controls & cooling are a good example
 - HP's Superdome (class C servers)
 - blades in a rack
 - chip and board thermals reported to rack controller
 - multiple temperature and air flow sensors in the rack
 - servo controlled air flow paddles and numerous fans
 - rack controller
 - controls air flow rate and direction
 - via fan speed and paddle
 - » imagine an ink jet like device in a package
 - sprays coolant to chip hot spots – this stuff works now

ES Functions

- **Almost anything you can imagine**
 - **5 basic types of functions**
 - » capture input signals and process the data
 - » control peripheral circuitry
 - » network with other ES's or computers
 - e.g. sensor arrays in forest canopy
 - NASA study: where the heck is all the extra CO2 coming from?
 - and how much is sequestered in the diminishing forest
 - monitor tremors to predict earthquakes
 - monitor tremors to predict volcanic activity
 - monitor your car
 - both fixed and ad-hoc networks
 - » user interfacing
 - something has to read that iPod click wheel
 - or display that new episode of Desperate Housewives
 - » data storage
- **Most ES's perform more than one of these functions**
 - often with a real-time constraint

Processors

- >99% are placed in ES's
- CNET's Top 10 Must-haves (prices approx.)
 - iPod Touch (\$360)
 - Asus 1005HA netbook (\$330)
 - Flip UltraHD (mini camcorder - \$190)
 - HTC Hero (Android phone - \$300)
 - LG enV Touch (phone - \$300)
 - Logitech Harmony One (RF remote - \$200)
 - Logitech Squeezebox Boom (WIFI radio - \$300)
 - Monster Turbine Pro (big bass ear bud - \$250)
 - Nintendo DSi (portable game gizmo - \$170)
 - Panasonic TC-P50G10 (HDTV - \$1400)
- Notice any trends?

Other Industries

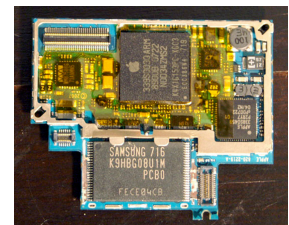
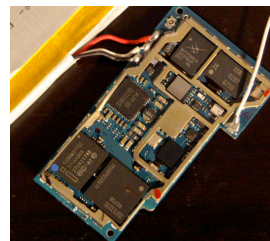
- Automotive
 - air bag controllers, ABS & traction control, engine management
 - » ~50 processors in luxury cars
 - heck my F250 plain Jane truck has
 - 2 processors per wheel
 - 2 airbag CPUs
 - 2 ECUs, 2 cruise controllers, + 1 in the radio
 - 0 CPUs in a **farmers truck**? go figure
 - why? digital control is flexible, reliable, and cheap
 - » CAN bus is on the move
 - every light has a 4-bit controller
- Communications
 - cell phones are very complex ES's
 - » codec's, DSP (IDCT, Rake, Turbo/Viterbi, ...), GPS ...
 - base station has lots of controllers as well

Others

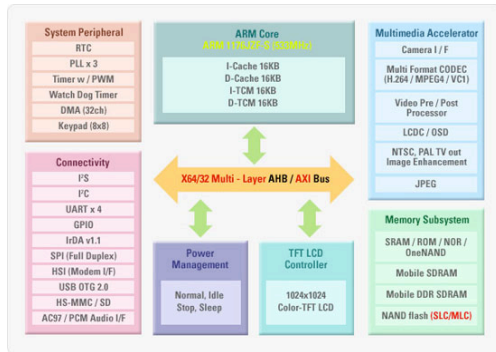
- Industrial
 - robotics
 - plant monitoring
 - » production optimization
 - » critical safety controls (e.g. nuclear, chemical, ...)
- Commercial
 - inventory management - RFID tags on Walmart pallets
 - point of sale systems
- Medical
 - life support monitors
 - medical testing
- CSI Hoboken
- Military
 - drones, ATR, G&C, GPS, fighter laser networks,
 - too bad this list is endless - then there's DHS (sheesh)

iPhone Dissected

<http://www.anandtech.com/printarticle.aspx?i=3026>



iPhone (cont'd)



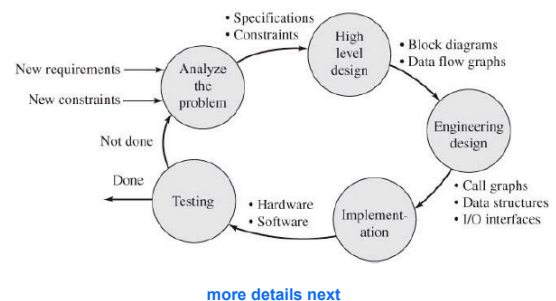
Embedded System Design

- **What makes It unique?**
 - **physically constrained computation**
 - » **timing deadlines & SWAP constraints**
 - **SWAP = size, weight, and power**
 - **traditional abstraction**
 - » **separate software from the HW and environment doesn't work**
 - **HW, SW, & environment**
 - » **tightly intertwined**
 - » **designers must understand the whole space**
- **Great read**
 - **"The Embedded Systems Design Challenge"**
 - » **Henzinger and Sifakis**
 - **continues this discussion**
- **5780 goal**
 - **start this "understanding" process**
 - **5785 continues this process**

Blatant and Shameless Hook

- **Symmetry In CPU's and Jobs**
 - **>99% of CPU's are in ES's**
 - **>99% of the computer jobs may be in ES design as well**
 - » **note the trend**
 - **# of computer companies is not growing**
 - **growth of gizmo companies is rampant**
- **OK**
 - **end of motivational diatribe**

Top-Down Design Process



Analysis Phase

- **Discover the requirements and constraints**
 - **Requirements**
 - » general parameters that the system must satisfy
 - transfer function view
 - what are the inputs and outputs
 - **Specifications**
 - » detailed & specific requirements
 - electrical signaling levels
 - mechanical interfaces
 - what functions must the device perform
 - **Constraints**
 - » e.g. SWAP constraints
 - » environmental issues affecting packaging
 - time for the Schlumberger sour well story
 - example of failure to understand the environment

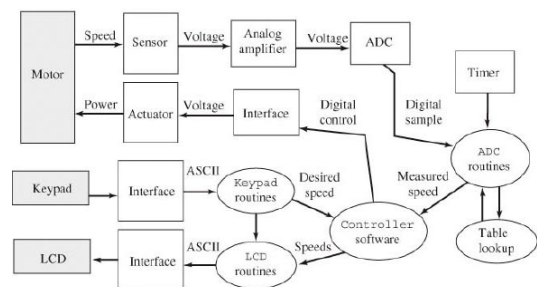
ES Design Metrics

- **NRE cost (engineering cost)**
- **WCT cost (whole cost transfer - \$ to make it)**
- **SWAP**
- **Performance (accuracy, precision, resolution, response time, bandwidth ...)**
- **The “billities”**
 - **flexible, maintainable, reliable, testable, compatible**
- **Time**
 - **to prototype, to market**
- **Safety**
 - **LI batteries blow up w/ toxic contents if not charged properly**
- **User Interface**
 - **look and feel**

High Level Design Phase

- **Build conceptual mode of the HW and SW system**
 - **design decomposition**
 - » define subsystems
 - » define interfaces (as in *precisely*)
- **Estimate**
 - **cost, schedule, performance**
- **Develop**
 - **data flow graph for the entire system**

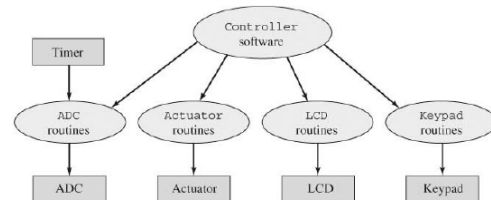
DFG for a Motor Controller



Engineering Design Phase

- **Construct a preliminary design**
 - **Includes**
 - » design hierarchy
 - » I/O signals
 - » shared data structures
 - » overall software scheme
 - » power requirements & distribution model
- **Build mock-ups (not a prototype)**
 - both mechanical parts and electrical HW
 - software
 - » both for core function and user interface
- **Call graphs**
 - explicit description of how HW & SW modules interact

Motor Controller Call Graph



Implementation Phase

- **Build the prototype**
 - note some of this could have been started in the design phase
 - » depends on project complexity
- **This can be a very difficult phase**
 - extensive simulation helps in the complex case
 - » HW & SW simulation
 - » cosimulation
 - essential in the very complex case
 - analysis tools are also helpful
 - » mechanical stress testing
 - » power analysis of electrical components
 - » etc.

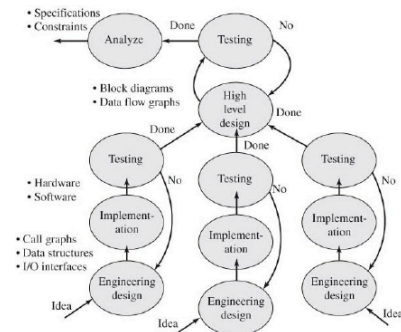
Testing Phase

- **Evaluate how well it works**
 - debug and validate functionality
 - » It MUST work as specified or nothing else matters
 - measure to test compliance of constraints
 - » SWAP
 - » and perhaps some environmental issues
 - final packaging may not yet be in place
 - but vibration, noise sensitive, RF emissions, ... come into play
 - optimize various performance parameters
 - » execution speed, accuracy, stability

Maintenance Phase

- **Basic tasks**
 - **correct mistakes**
 - **add new features as required**
 - **further optimization of performance, program size, etc.**
 - **port to new HW or OS platform**
 - » **e.g. new rev of previous system**
 - » **deal with changes in requirements or constraints**
 - common pain experienced even before 1st release
 - culprits: management, market swing, competition
- **2 possibilities for this phase**
 - **real phase for a released system**
 - **more passes around the loop due to mandated changes**

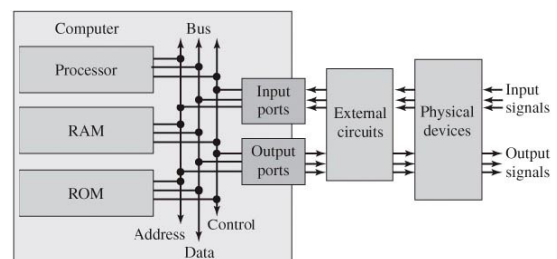
Bottom-Up Design Process



Probable Design Process

- **Neither bottom-up or top-down**
 - **Ideas come from both directions**
 - » **bottom: what technology induced opportunities exist**
 - » **top: what the market or a specific customer wants**
 - **meeting in the middle in a balanced way is tricky**
 - » **but it's the game that is played**
- **Hence design is a Yo-Yo**
 - **up-down repeat as necessary**

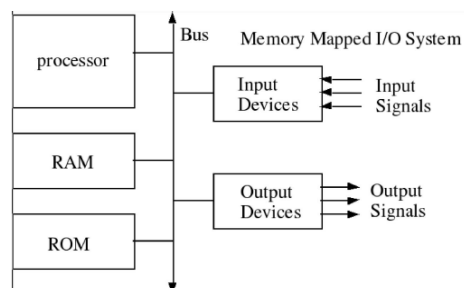
Basic System Components



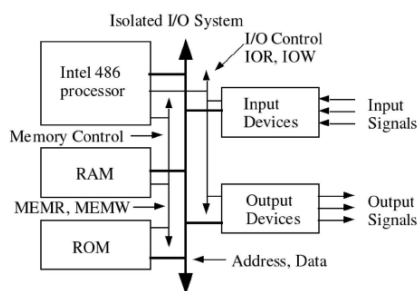
Memory Map

- **Processor sources the address & R/W bit**
 - **but who responds?**
- **Answer partition the memory space**
 - **example**
 - » \$0000-\$00FF & Read: read input port values
 - » \$0000-\$00FF & Write: send data to output ports
 - » \$0100-\$0FFF – read or write RAM
 - » \$1000-\$FFFF – read or write ROM
- **Actual map is usually device dependent**
 - **also usually fixed**
 - **but sometimes user can customize map to some extent**

Memory-Mapped System



Isolated I/O System

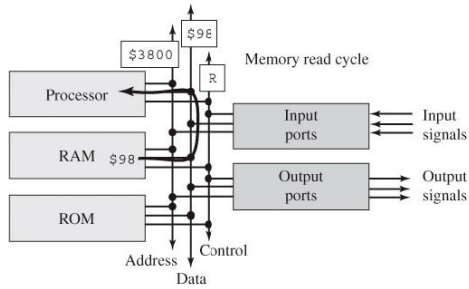


More pins but safer – why?

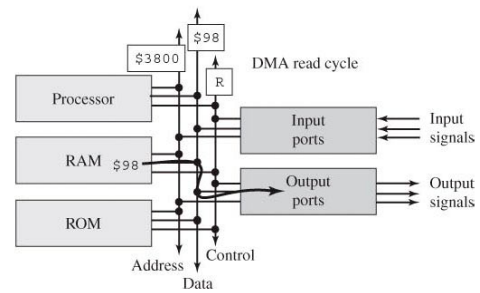
Memory & I/O Essential Differences

- **True even when memory is off-chip**
- **Memory operations can be reordered**
 - **as long as hazards are avoided**
 - » RAW, WAR, WAW
 - » RAR can always be reordered
 - **note that the compiler does this**
 - » **Inherent part of optimization**
 - » **It knows about hazards and how they can be hidden by futzing with pointers**
 - **a.k.a. obfuscated code**
- **I/O operations inherently have side effects**
 - **effectively pseudo-commands**
 - **must be done in-order and EXACTLY once**
 - » **so your code will need to tell the compiler somehow to not optimize this for non-I/O isolated systems**
 - **we'll cover this in more detail later in the course**

Memory Read Cycle



DMA Read Cycle



Concluding Remarks

- **ES design is different**
 - **HW/SW/environment Intertwine**
 - » normal abstract partition wall isn't in place
 - **I/O is a much bigger piece of the game**
 - » system model is different
 - » CPU is a controller rather than the center of work
 - **relatively fixed function**
 - » since the peripheral circuitry & components are fixed
 - » control can change but this has a minor effect on system capability
 - **reliability is held to much higher standards**
 - » Inputs say "reactor is going critical"
 - » controller says "can't pull the rods - gotta reboot"

