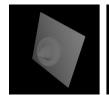
A Hybrid Approach

One more shadow algorithm which deserves mention is McCool's clever idea shadow volume reconstruction from depth maps [McCool 2000].

This algorithm is a hybrid of the shadow map and shadow volume algorithms and **does not require a polygonal representation of the scene**.

□ Instead of finding the silhouette edges via a dot product per model edge (shadow volumes), a depth map of the scene from the light's point of view is acquired (shadow map) from which the silhouette edges are extracted using computer vision techniques. From these edges the shadow volumes are constructed (silhouette edges are extruded)





Creating soft shadows

Soft vs. hard shadows

Common sense: binary status of shadow

But it looks very unrealistic

Real picture

Why?





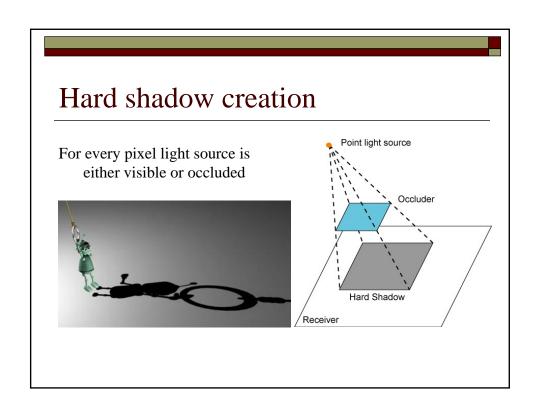
Soft vs. hard shadows.

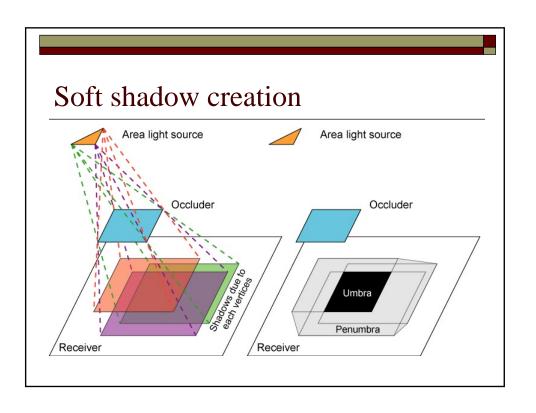
In real life light sources are not points.

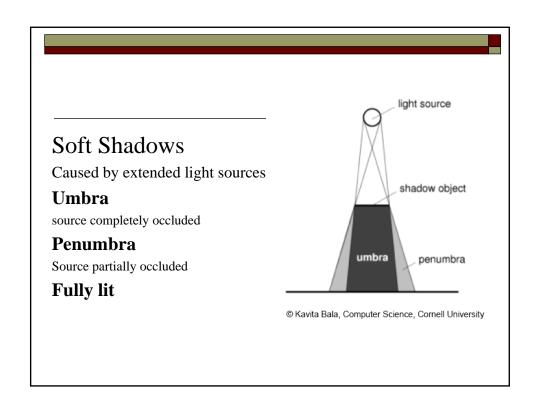


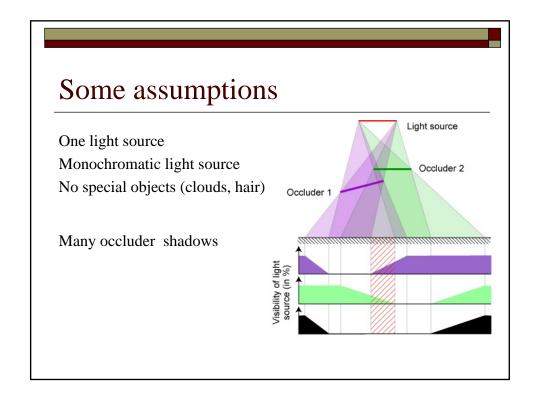












Shadow map algorithm

Point of view of the light source

Method:

Z-buffer from light source is stored to shadow map buffer

Z-buffer from spectator

Comparison distance to light source with shadow map





Shadow volume algorithm

Geometrical representation

Extruding of silhouettes creates shadow volume

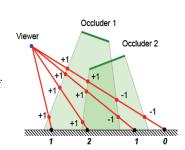
Method:

Find silhouettes of occluders

Extruding silhouettes to shadow volumes

For every pixel number of crossed faces of shadow volumes counted

If number of total number of faces if positive we are in shadow



Light source

Soft shadow algorithms

Image-based approach (based on shadow map algorithm)

Object-based approach (based on shadow volume algorithms

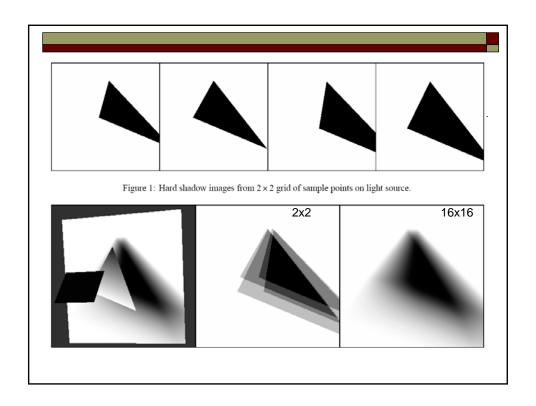
Image-based approach

Combining some shadow maps from point samples

Layered shadow maps instead of shadow map

Some shadow maps take from point samples and computing percentage of light source visibility

Using standard shadow map with techniques to compute soft shadow



Combining point light sources

The simplest method by Herf (1997)

Method

For every sample compute binary occlusion map

Computing attenuation map storing for every pixel how many light source samples occluded







Combining point light sources



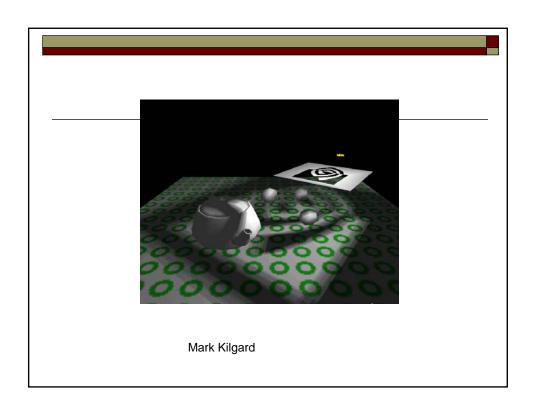


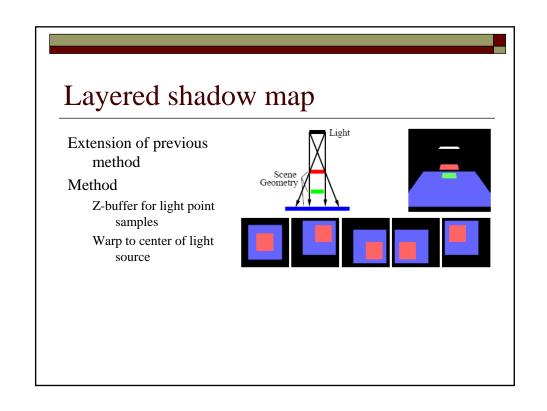
Time complexion (NsNp for attenuation map)
With fewer than 9 samples user sees number of hard shadows
Parralelizable

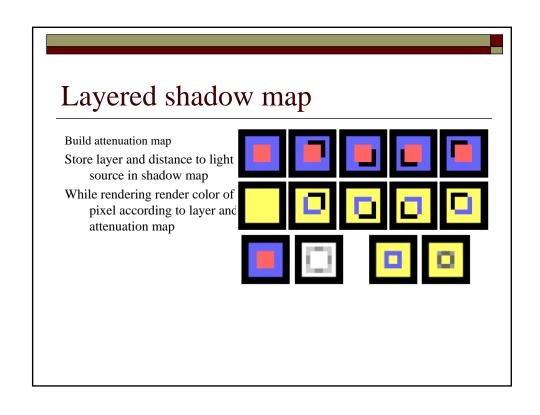


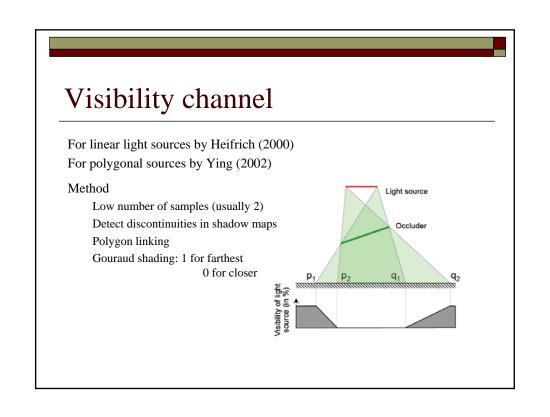


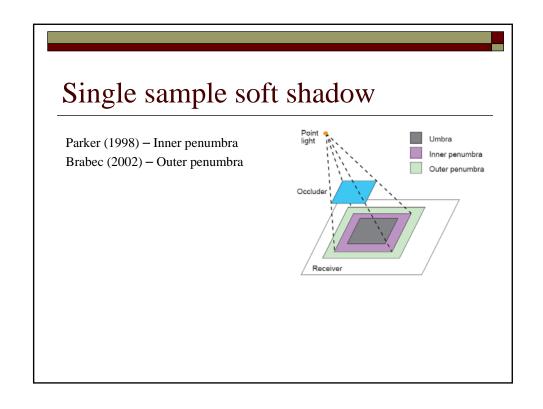
Heckbert & Herf

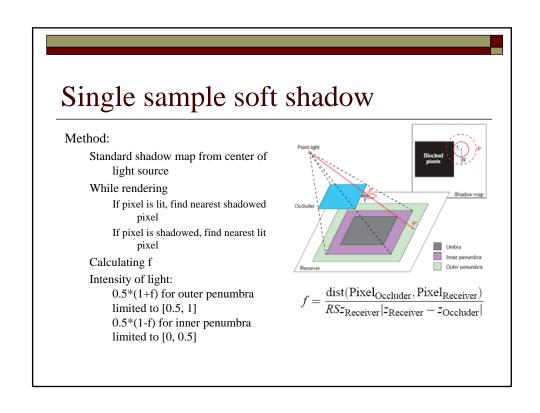












Single sample soft shadow

Disadvantages:

Bottleneck: to find nearest lit/shadowed pixel

Doesn't depend on size of light source, only from distances

Object based approach

Combining some hard shadows

Extending shadow volume by heuristic

Computing penumbra volume for each edge

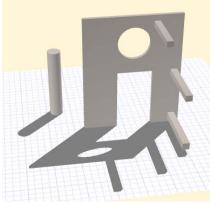
Combining hard shadows

The simplest method to produce soft shadow Method:

Several light source samples Build shadow volumes for each sample Average received pictures

Plateau Soft Drop Shadows

Say we want to paint a soft shadow for an image.



Soft planar shadows

Haines (2001)

Planar receiver

Method

Standard shadow volume algorithm

Vertices of silhouette turned to cones

Building edges around cones

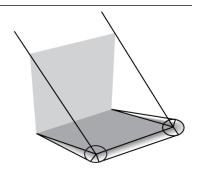
Disadvantages:

Planar surfaces

Spherical light source

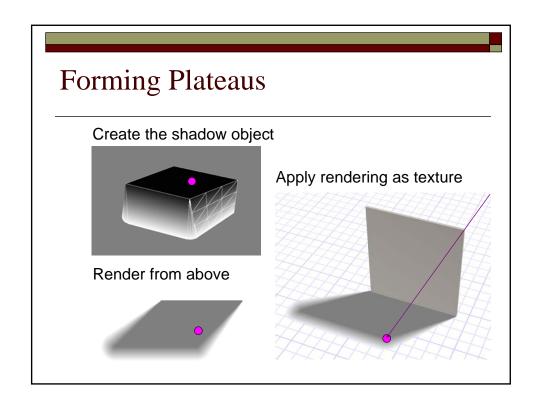
Outer penumbra

Penumbra depends only from distance occluderreceiver



Plateau Idea

"Paint" each shadow's edge, blurring it as its height from the plane increases.



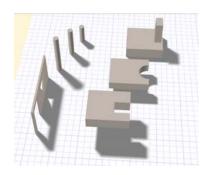
Plateau Result

Soft shadows, at the cost of finding the silhouette and drawing cones & sheets.



Plateau Limitations

Overstated umbrae, penumbrae are not physically correct, and like Nguyen.





Plateau Shadows (1 pass) Heckbert/Herf (256 passes)

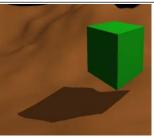
Penumbra Maps

Builds on simple idea of "shadow plateaus" introduced by Haines ('01) Plausible soft shadows

Hard upon contact, soft with distance Simple implementation on graphics hardware

Hides some aliasing

One sample per pixel





Penumbra Map Assumptions

A hard shadow is a reasonable approximation for a shadow's umbra

Object silhouettes remain constant over light's surface

Key Insight

When using a hard shadow as the umbra, all of the approximate penumbra is visible from the center of the light

Allows storage of penumbral intensity in a separate map we call a *penumbra map*





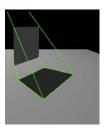
Creating Penumbra Map

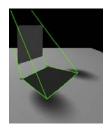
Compute shadow map (for hard shadow)

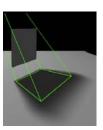
Compute object silhouette from light's center

Compute cones at silhouette vertices

Compute sheets connecting vertices (along silhouette edges)







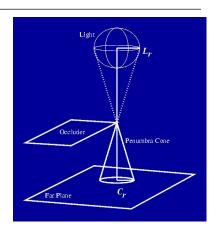
Computing Cones

For each silhouette vertex

Find distance from light's center to vertex

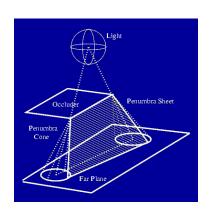
Find distance from vertex to far plane

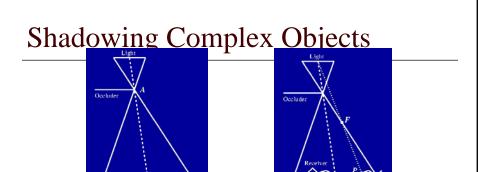
Using these distances and the light radius L_r compute C_r using similar triangles



Computing Sheets

Create quads at each silhouette edge tangent to the adjacent cones
May not be planar
Subdivide significantly non-planar quads for good results





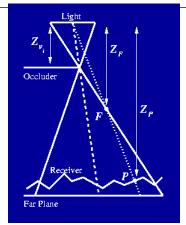
Can not just draw quad with 0 (shadowed) at A and 1 (illuminated) at C

Result depends on current fragment F on quad and point P in the shadow map

Use Fragment Program to Generate Map

```
FragmentProgram(Z_{v_i}, F, S_{map})
        F_{coord} = GetWindowCoord(F)
        Z_P = TextureLookup(S_{map}, F_{coord})
(2)
        Z_F = F_{coord_z}
(3)
```

- if $(Z_F > Z_P)$ DiscardFragment() (4) (5) $Z_P' = Convert To World Space(Z_P)$
- (6) $Z'_F = Convert To World Space(Z_F)$
- $I = (Z'_F Z_{v_i}) / (Z'_P Z_{v_i})$ $I' = 3I^2 2I^3$ (7)
- (8)
- $Output_{color} = I'$ (9)
- $Output_{depth} = I'$

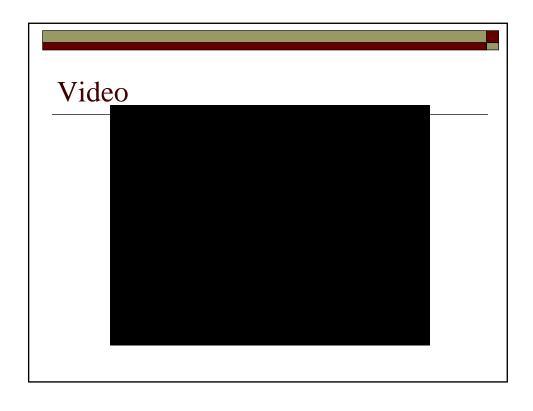


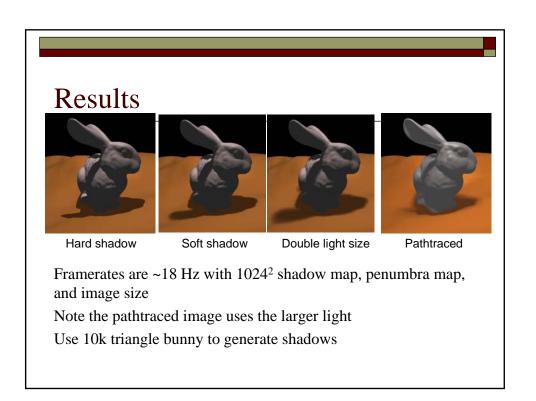
Rendering

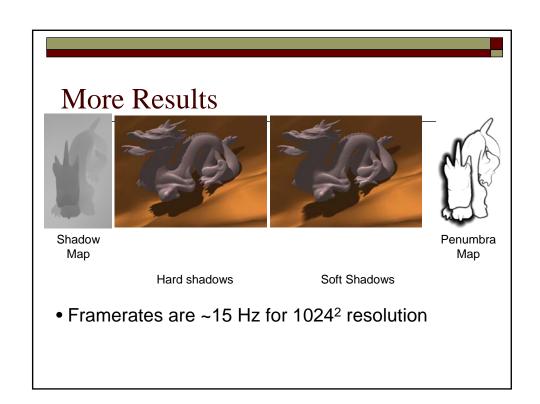
Compare fragment's depth to shadow map to determine if light is completely blocked

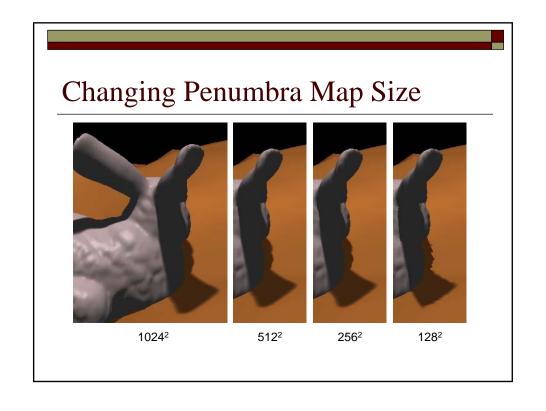
If not completely shadowed, index into penumbra map to determine percentage of light reaching surface

Multiple lights requires multiple shadow and penumbra maps









Problems

Shadows are not accurate

Less accurate as occluders move further away from shadowed objects

Assume silhouettes constant over light

Noticeable pops on cube

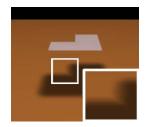
No problems with other objects

Blending overlapping penumbrae

Occurs on a per-pixel basis

No geometric info in the hardware

Artifacts at silhouette concavities



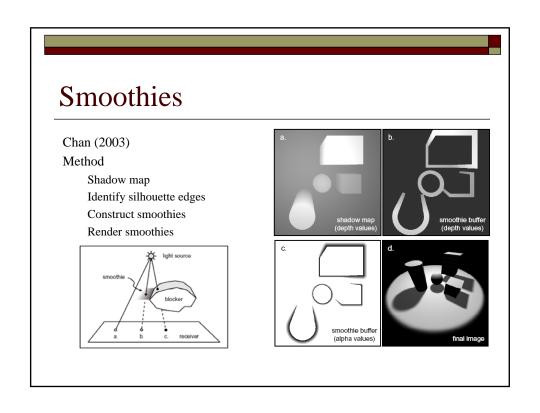


In these three cases, overlapping penumbrae should be handled differently

No geometric information in the pixel program means no quick way to decide in hardware

We always choose the darkest pixel (left image)

Same as Smoothies....



Smoothies Disadvantages Outer penumbra only There is always umbra Connecting edges Smoothie edge Smoothie edge Smoothie corner

Video

Comparison to Penumbra Maps

Penumbra maps (Wyman and Hansen, EGSR 2003)

Same idea, different details

Penumbra Maps Smoothies

Geometry:

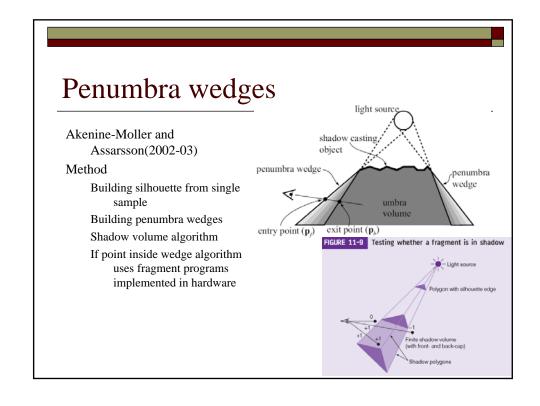
cones and sheets quads

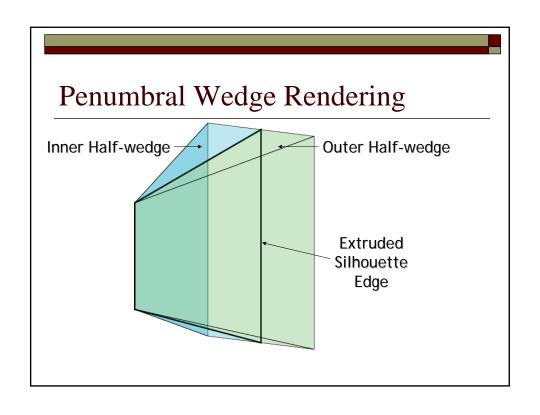
Store depth: blockers only

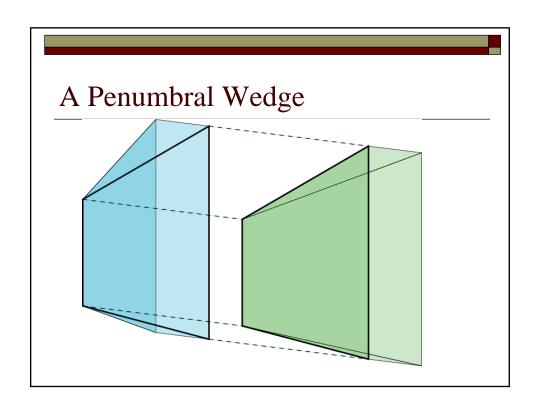
blockers + smoothies

Smoothie depth:

- Extra storage + comparison
- Handles surfaces that act only as receivers







Soft Shadow Correction

Darken area inside outer penumbra Lighten area inside inner penumbra



Soft Shadow Correction

Lighting pass for ordinary stencil shadows uses stencil test

0 in stencil buffer at a particular pixel means light can reach that pixel

Nonzero means pixel is in shadow

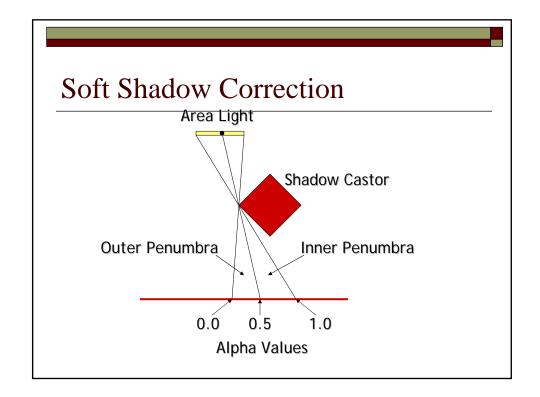
Soft Shadow Correction

For soft shadows, we use alpha blending during lighting pass

Value in the alpha channel represents how much of the area light is covered

0 means entire light source visible from a particular pixel

1 means no part of light source is visible (fully shadowed)



Soft Shadow Correction

Render the shadow volumes into a 16-bit floating-point render target

Penumbral Wedge Rendering

In the vertex program, we compute the three outside bounding planes of a half-wedge Send these planes to the fragment program in viewport space!

Allows us to do a quick test to determine whether a viewport-space point is outside the half-wedge

Penumbral Wedge Rendering

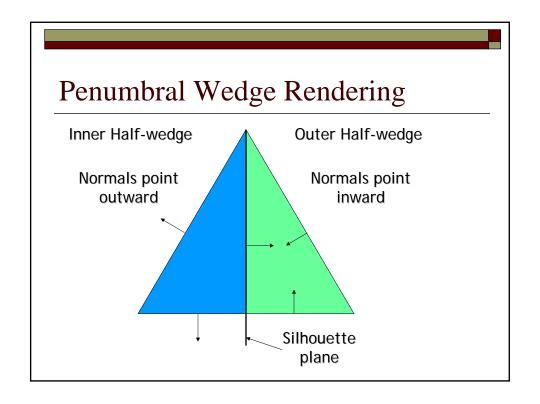
In the fragment program, we test the viewportspace position of the point in the frame buffer against three half-wedge bounding planes We will use the depth test to reject points on the wrong side of the extruded silhouette edge

Penumbral Wedge Rendering

Sort half-wedges into two batches:

- 1) Those for which camera is on the positive side of the silhouette edge
- 2) Those for which camera is on the negative side of the silhouette edge

Extruded silhouette plane normal always points outward from shadow volume



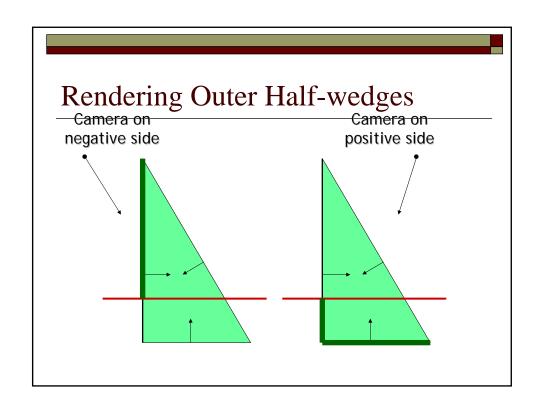
Rendering Outer Half-wedges

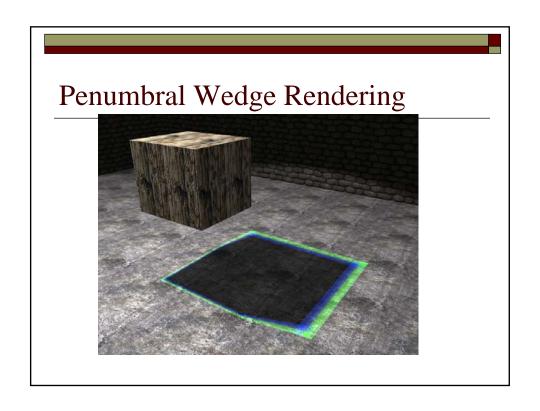
Half-wedges for which camera is on positive side of silhouette plane

Render front faces when z test fails

Half-wedges for which camera is on negative side of silhouette plane

Render back faces when z test passes





Penumbral Wedge Rendering

If the value was greater than one, then it's saturated to one, corresponding to fully shadowed

Then render lighting pass, multiplying source color by one minus destination alpha

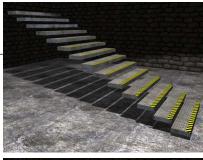
glBlendFunc(GL_ONE_MINUS_DST_ALPHA, GL_ONE);

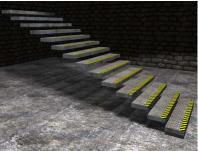
Small Light Area

Shadows sharper, rendering faster

Large Light Area

Shadows softer, interact more, rendering slower





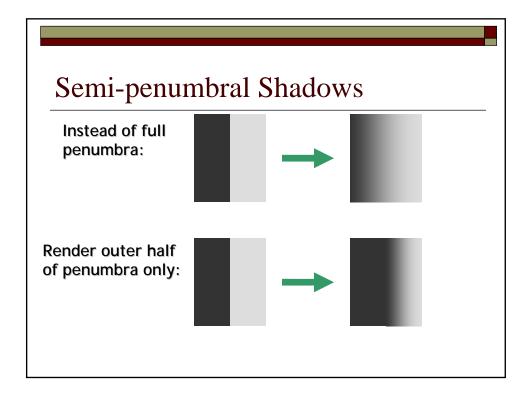
Semi-penumbral Shadows

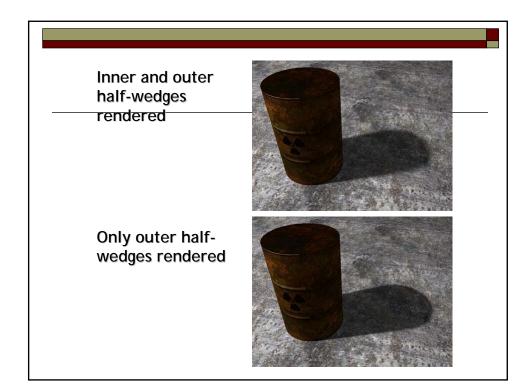
Method for speeding up penumbral wedge soft shadows

Only render outer half-wedges

Less correct, but still looks good

Lose the ability to cast shadows that have no point of 100% light occlusion





Summary

Hard vs. soft shadows
Existing algorithms for soft shadow creation
Advantages and disadvantages of each algorithms

Bibliography

Maneesh Agrawala, Ravi Ramamoorthi, Alan Heirich and Laurent Moll. Efficient image-based methods for rendering soft shadows.

Tomas Akenine-Möller and Ulf Assarsson. Approximate soft shadows on arbitrary surfaces using penumbra wedges.

Eric Chan and Fredo Durand. Rendering fake soft shadows with smoothies.

J.-M. Hasenfratz, M. Lapierre, N. Holzschuch and F.X. Sillion A Survey of Real-time Soft Shadows Algorithms