## A Hybrid Approach

One more shadow algorithm which deserves mention is McCool's clever idea shadow volume reconstruction from depth maps [McCool 2000].
This algorithm is a hybrid of the shadow map and shadow volume algorithms and does not require a polygonal representation of the scene.
$\square$ Instead of finding the silhouette edges via a dot product per model edge (shadow volumes), a depth map of the scene from the light's point of view is acquired (shadow map) from which the silhouette edges are extracted using computer vision techniques. From these edges the shadow volumes are constructed (silhouette edges are extruded)

## Creating soft shadows

## Soft vs. hard shadows

Common sense: binary status of shadow

But it looks very unrealistic


Real picture

Why?


Soft vs. hard shadows.

In real life light sources are not points.


## Hard shadow creation

For every pixel light source is either visible or occluded


## Soft shadow creation



## Soft Shadows

Caused by extended light sources

## Umbra

source completely occluded
Penumbra
Source partially occluded
Fully lit

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## Some assumptions

One light source
Monochromatic light source
No special objects (clouds, hair)


## Shadow map algorithm

Point of view of the light source

## Method:

Z-buffer from light source is stored to shadow map buffer
Z-buffer from spectator
Comparison distance to light source with shadow map


## Shadow volume algorithm

Geometrical representation

- Light source

Extruding of silhouettes creates shadow volume
Method:
Find silhouettes of occluders
Extruding silhouettes to shadow volumes
For every pixel number of crossed faces of shadow volumes counted
If number of total number of faces if positive we are in shadow


## Soft shadow algorithms

Image-based approach (based on shadow map algorithm)
Object-based approach (based on shadow volume algorithms

## Image-based approach

Combining some shadow maps from point samples
Layered shadow maps instead of shadow map
Some shadow maps take from point samples and computing percentage of light source visibility
Using standard shadow map with techniques to compute soft shadow


Figure 1: Hard shadow images from $2 \times 2$ grid of sample points on light source.


## Combining point light sources

The simplest method by Herf (1997)
Method
For every sample compute binary occlusion map
Computing attenuation map storing for every pixel how many
light source samples occluded


## Combining point light sources



Time complexion (NsNp for attenuation map)
With fewer than 9 samples user sees number of hard shadows
Parralelizable



Mark Kilgard

## Layered shadow map

Extension of previous method
Method
Z-buffer for light point samples
Warp to center of light source


## Layered shadow map



## Visibility channel

For linear light sources by Heifrich (2000)
For polygonal sources by Ying (2002)
Method
Low number of samples (usually 2 )
Detect discontinuities in shadow maps
Polygon linking
Gouraud shading: 1 for farthest 0 for closer


## Single sample soft shadow

Parker (1998) - Inner penumbra
Brabec (2002) - Outer penumbra


## Single sample soft shadow

Method:
Standard shadow map from center of light source

While rendering
If pixel is lit, find nearest shadowed pixel
If pixel is shadowed, find nearest lit pixel
Calculating f
Intensity of light:
$0.5^{*}(1+\mathrm{f})$ for outer penumbra
limited to [0.5, 1]
$0.5^{*}(1-\mathrm{f})$ for inner penumbra
limited to [0, 0.5]


$$
f=\frac{\text { dist }\left(\text { Pixel }_{\text {Occluder }}, \text { Pixel }_{\text {Receiver }}\right)}{R S z_{\text {Receiver }}\left|z_{\text {Receiver }}-z_{\text {Occluder }}\right|}
$$

## Single sample soft shadow

## Disadvantages:

Bottleneck: to find nearest lit/shadowed pixel
Doesn't depend on size of light source, only from distances


## Object based approach

Combining some hard shadows
Extending shadow volume by heuristic
Computing penumbra volume for each edge

## Combining hard shadows

The simplest method to produce soft shadow
Method:
Several light source samples
Build shadow volumes for each sample
Average received pictures

## Plateau Soft Drop Shadows

Say we want to paint a soft shadow for an image.


## Soft planar shadows

Haines (2001)
Planar receiver
Method
Standard shadow volume algorithm
Vertices of silhouette turned to cones
Building edges around cones
Disadvantages:
Planar surfaces


Spherical light source
Outer penumbra
Penumbra depends only from distance occluderreceiver

## Plateau Idea

"Paint" each shadow's edge, blurring it as its height from the plane increases.


## Forming Plateaus

Create the shadow object


Render from above


Apply rendering as texture


## Plateau Result

Soft shadows, at the cost of finding the silhouette and drawing cones \& sheets.


## Plateau Limitations

Overstated umbrae, penumbrae are not physically correct, and like Nguyen.


Plateau Shadows (1 pass) Heckbert/Herf (256 passes)

## Penumbra Maps

Builds on simple idea of "shadow plateaus" introduced by Haines ('01) Plausible soft shadows
Hard upon contact, soft with distance
Simple implementation on graphics hardware

Hides some aliasing
One sample per pixel


## Penumbra Map Assumptions

A hard shadow is a reasonable approximation for a shadow's umbra

Object silhouettes remain constant over light's surface

Key Insight
When using a hard shadow as the umbra, all of the approximate penumbra is visible from the center of the light
Allows storage of penumbral intensity in a separate map we call a penumbra map


## Creating Penumbra Map

Compute shadow map (for hard shadow)
Compute object silhouette from light's center
Compute cones at silhouette vertices
Compute sheets connecting vertices (along silhouette edges)


## Computing Cones

For each silhouette vertex
Find distance from light's center to vertex

Find distance from vertex to far plane
Using these distances and the light radius $\mathrm{L}_{\mathrm{r}}$ compute $\mathrm{C}_{\mathrm{r}}$ using similar triangles


## Computing Sheets

Create quads at each silhouette edge tangent to the adjacent cones
May not be planar
Subdivide significantly nonplanar quads for good results


## Shadowing Complex Objects



Can not just draw quad with 0 (shadowed) at A and 1 (illuminated) at C
Result depends on current fragment F on quad and point $P$ in the shadow map

## Use Fragment Program to Generate Map

FragmentProgram $\left(Z_{v_{i}}, F, S_{\text {map }}\right)$
(1) $\quad F_{\text {coord }}=\operatorname{GetWindowCoord}(F)$
(2) $Z_{P}=$ TextureLookup $\left(S_{\text {map }}, F_{\text {coord }}\right)$
(3) $Z_{F}=F_{\text {coord }_{z}}$
(4) if $\left(Z_{F}>Z_{P}\right)$ DiscardFragment()
(5) $\quad Z_{P}^{\prime}=$ ConvertToWorldSpace $\left(Z_{P}\right)$
(6) $\quad Z_{F}^{\prime}=$ ConvertToWorldSpace $\left(Z_{F}\right)$
(7) $\quad I=\left(Z_{F}^{\prime}-Z_{v_{i}}\right) /\left(Z_{P}^{\prime}-Z_{v_{i}}\right)$
(8) $I^{\prime}=3 I^{2}-2 I^{3}$
(9) $\quad$ Output $_{\text {color }}=I^{\prime}$
(10) Output $_{\text {depth }}=I^{\prime}$


## Rendering

Compare fragment's depth to shadow map to determine if light is completely blocked

If not completely shadowed, index into penumbra map to determine percentage of light reaching surface

Multiple lights requires multiple shadow and penumbra maps

## Video



## Results



Hard shadow


Soft shadow


Double light size


Pathtraced

Framerates are $\sim 18 \mathrm{~Hz}$ with $1024^{2}$ shadow map, penumbra map, and image size
Note the pathtraced image uses the larger light
Use 10k triangle bunny to generate shadows


More Results


Shadow
Map
Hard shadows



Penumbra Map

Soft Shadows

- Framerates are $\sim 15 \mathrm{~Hz}$ for $1024^{2}$ resolution

Changing Penumbra Map Size

$1024^{2}$

$512^{2}$

$256^{2}$

$128^{2}$

## Problems

## Shadows are not accurate

Less accurate as occluders move further away from shadowed objects

## Assume silhouettes constant over light

Noticeable pops on cube
No problems with other objects
Blending overlapping penumbrae
Occurs on a per-pixel basis
No geometric info in the hardware
Artifacts at silhouette concavities


Blending Issues


In these three cases, overlapping penumbrae should be handled differently
No geometric information in the pixel program means no quick way to decide in hardware
We always choose the darkest pixel (left image)

## Same as Smoothies....



## Smoothies

Chan (2003)
Method
Shadow map
Identify silhouette edges
Construct smoothies
Render smoothies


Smoothies

## Disadvantages

Outer penumbra only
There is always umbra
Connecting edges


## Video

## Comparison to Penumbra Maps

Penumbra maps (Wyman and Hansen, EGSR 2003)

- Same idea, different details

Penumbra Maps Smoothies
Geometry:
Store depth:

| cones and sheets | quads |
| :---: | :---: |
| blockers only | blockers + smoothies |

Smoothie depth:

- Extra storage + comparison
- Handles surfaces that act only as receivers


## Penumbra wedges

Akenine-Moller and
Assarsson(2002-03)
Method
Building silhouette from single sample
Building penumbra wedges
Shadow volume algorithm
If point inside wedge algorithm uses fragment programs implemented in hardware


## Penumbral Wedge Rendering



A Penumbral Wedge


## Soft Shadow Correction

Darken area inside outer penumbra
Lighten area inside inner penumbra


## Soft Shadow Correction

Lighting pass for ordinary stencil shadows uses stencil test

0 in stencil buffer at a particular pixel means light can reach that pixel
Nonzero means pixel is in shadow

## Soft Shadow Correction

For soft shadows, we use alpha blending during lighting pass
Value in the alpha channel represents how much of the area light is covered
0 means entire light source visible from a particular pixel
1 means no part of light source is visible (fully shadowed)

## Soft Shadow Correction



## Soft Shadow Correction

Render the shadow volumes into a 16-bit floating-point render target

## Penumbral Wedge Rendering

In the vertex program, we compute the three outside bounding planes of a half-wedge Send these planes to the fragment program in viewport space!
Allows us to do a quick test to determine whether a viewport-space point is outside the half-wedge

## Penumbral Wedge Rendering

In the fragment program, we test the viewportspace position of the point in the frame buffer against three half-wedge bounding planes We will use the depth test to reject points on the wrong side of the extruded silhouette edge

## Penumbral Wedge Rendering

Sort half-wedges into two batches:

1) Those for which camera is on the positive side of the silhouette edge
2) Those for which camera is on the negative side of the silhouette edge
Extruded silhouette plane normal always points outward from shadow volume

## Penumbral Wedge Rendering



## Rendering Outer Half-wedges

Half-wedges for which camera is on positive side of silhouette plane
Render front faces when $z$ test fails

Half-wedges for which camera is on negative side of silhouette plane
Render back faces when $z$ test passes

## Rendering Outer Half-wedges


$\square$
Penumbral Wedge Rendering


## Penumbral Wedge Rendering

If the value was greater than one, then it's saturated to one, corresponding to fully shadowed

Then render lighting pass, multiplying source color by one minus destination alpha

glBlendFunc(GL_ONE_MINUS_DST_ALPHA, GL_ONE);



## Semi-penumbral Shadows

Method for speeding up penumbral wedge soft shadows

Only render outer half-wedges
Less correct, but still looks good
Lose the ability to cast shadows that have no point of $100 \%$ light occlusion



## Summary

Hard vs. soft shadows
Existing algorithms for soft shadow creation
Advantages and disadvantages of each algorthms

## Bibliography

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