

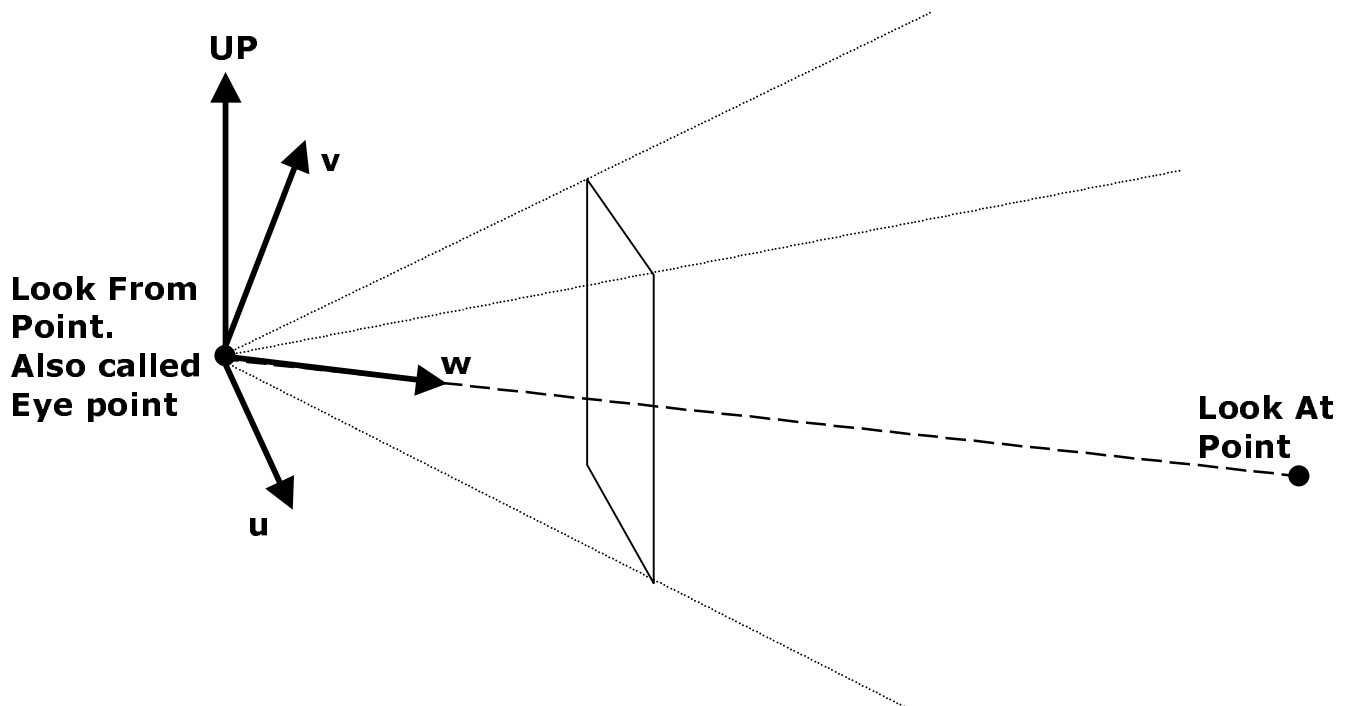
Perspective Transformations

Viewing system matrix \mathbf{M}_{sys} transform is obtained by combining the view matrix with the perspective projection with the viewport to screen matrix. These are defined as:

$$\mathbf{M}_{\text{sys}} = \mathbf{M}_{\text{screen}} \mathbf{M}_{\text{perspective}} \mathbf{M}_{\text{view}}$$

View Matrix

We want to compute the view matrix that aligns the orthonormal basis at the origin and pointing down either the +Z (right-handed) or -Z (left-handed). Here's the picture:



To form the view transform, the axes for the coordinate system of are given by (for right hand system):

$$W = \frac{\text{eye} - \text{at}}{\|\text{eye} - \text{at}\|}$$

$$U = \frac{\text{up} \times w}{\|\text{up} \times w\|}$$

$$V = \frac{w \times u}{\|w \times u\|}$$

For a left-handed system:

$$W = \frac{\text{at} - \text{eye}}{\|\text{at} - \text{eye}\|}$$

$$U = \frac{\text{up} \times w}{\|\text{up} \times w\|}$$

$$V = \frac{u \times w}{\|u \times w\|}$$

$\begin{matrix} U_x & U_y & U_z & 0 \\ V_x & V_y & V_z & 0 \\ W_x & W_y & W_z & 0 \\ 0 & 0 & 0 & 1 \end{matrix}$	Orthonormal Rotation about origin
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$\begin{matrix} 1 & 0 & 0 & -eye_x \\ 0 & 1 & 0 & -eye_y \\ 0 & 0 & 1 & -eye_z \\ 0 & 0 & 0 & 1 \end{matrix}$	Translation to origin
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$\begin{matrix} U_x & U_y & U_z & 0 \\ V_x & V_y & V_z & 0 \\ W_x & W_y & W_z & 0 \\ 0 & 0 & 0 & 1 \end{matrix}$	*	$\begin{matrix} 1 & 0 & 0 & -eye_x \\ 0 & 1 & 0 & -eye_y \\ 0 & 0 & 1 & -eye_z \\ 0 & 0 & 0 & 1 \end{matrix}$	*	$\begin{matrix} \mathbf{VERTEX}_x \\ \mathbf{VERTEX}_y \\ \mathbf{VERTEX}_z \\ 1 \end{matrix}$
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