

Lecture 7: Synchronization

(Chapter 6)



Multi-level Feedback Queues

- Multiple queues with different priorities
 - Alternative: single priority queue
- Round robin schedule processes with equal priorities
 - Low priority jobs can "starve" for a while
- Adjust priorities based on observed behavior:
 - Jobs start with default priority (perhaps modified via "nice")
 - If time quantum expires, bump job priority down
 - If job blocks before end of time quantum, bump priority up (Why?)
- Effect:
 - The scheduler "figures out" which jobs are interactive and which are CPU-bound







What is Synchronization?

Question: How do you control the behavior of "cooperating" processes that share resources?

Time	You	Your roomate	
3:00	Arrive home		
3:05	Check fridge \rightarrow no milk		
3:10	Leave for grocery		
3:15		Arrive home	
3:20	Buy milk	Check fridge \rightarrow no milk	
3:25	Arrive home, milk in fridge	Leave for grocery	
3:30			
3:35		Buy milk	\sim
3:40		Arrive home, milk in fridge!	•



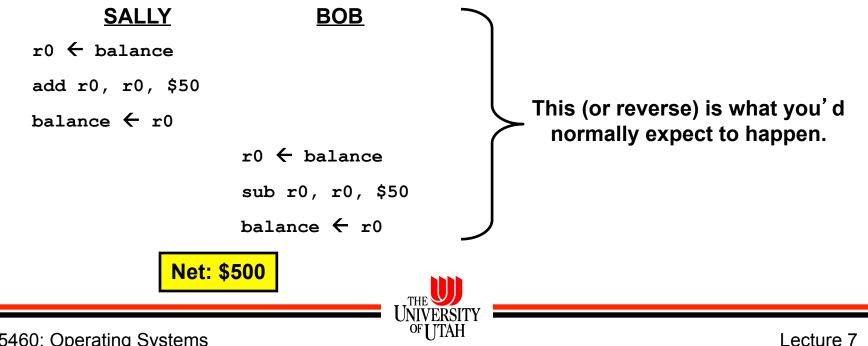
Shared Memory Synchronization

- Threads share memory
- Preemptive thread scheduling is a major problem
 - Context switch can occur at any time, even in the middle of a line of code (e.g., "X = X + 1;")
 - » Unit of atomicity \rightarrow Machine instruction
 - » Cannot assume anything about how fast processes make progress
 - Individual processes have little control over order in which processes run
- Need to be paranoid about what scheduler might do
- Preemptive scheduling introduces <u>non-determinism</u>



Race Condition

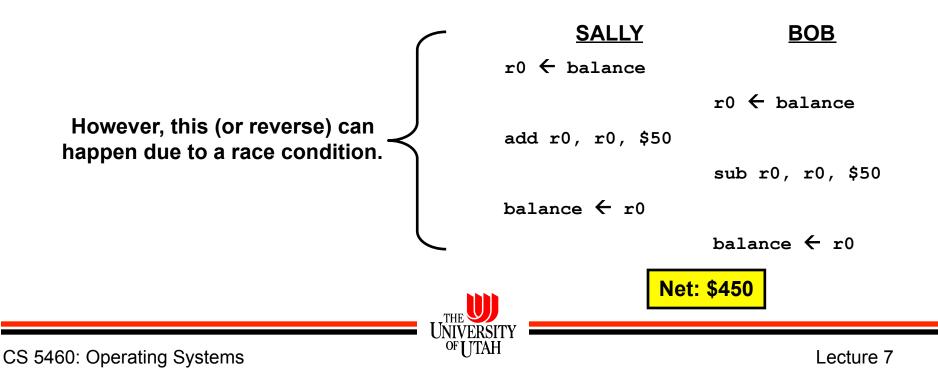
- Two (or more) processes run in parallel and output depends on order in which they are executed
- ATM Example
 - SALLY: balance += \$50; BOB: balance -= \$50;
 - <u>Question</u>: If initial balance is \$500, what will final balance be?



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Race Conditions

- Two (or more) processes run in parallel and output depends on order in which they are executed
- ATM Example
 - SALLY: balance += \$50; BOB: balance -= \$50;
 - <u>Question</u>: If initial balance is \$500, what will final balance be?





- The race condition happened because there were conflicting accesses to a resource
- Basic idea behind most synchronization:
 - If two threads, processes, interrupt handlers, etc. are going to have conflicting accesses, force one of them wait until it is safe to proceed
- Conceptually simple, but difficult in practice
 - The problem is that we need to protect all possible locations where two (or more) threads or processes might conflict



Synchronization Problems

Synchronization can be required for different resources

- <u>Memory</u>: e.g., multithreaded application
- <u>OS object</u>: e.g., two processes that read/write same system file
- <u>Hardware device</u>: e.g. two processes that both want to burn a DVD
- There are different kinds of synchronization problems
 - Sometimes we just want activities to not interfere with each other
 - Sometimes we care about ordering



Synchronization Problems

Synchronization may be across machines

- What if some machines are disconnected or rebooting?

Sometimes it's not OK to block a thread or process

- May have to reserve the "right" do something ahead of time



Atomic Operations

Series of operations that cannot be interrupted

- Some operations are atomic with respect to everything that happens on a machine
- Other atomic operations are atomic only with respect to conflicting processes, threads, interrupt handlers, etc.
- On typical architectures:
 - Individual word load/stores and ALU instructions
 - Synchronization operations (e.g., fetch_and_add, cmp_and_swap)

• ATM example \rightarrow Balance updates were NOT atomic

- Solution: Enforce atomic balance updates
- Question: How?



More Atomic

 Atomic operations are at the root of most synchronization solutions

Processor has to support some atomic operations

- If not, we're stuck!

- OS uses low-level primitives to build up more sophisticated atomic operations
 - For example, locks that support blocking instead of busy-waiting
 - We'll look at an example soon



More Definitions

- Synchronization (or Concurrency Control):
 - Using atomic operations to eliminate race conditions
- Critical section:
 - Piece of code (e.g., ATM balance update) that must run atomically
 - Mutual exclusion: Ensure at most one process at a time
- Lock:
 - Synchronization mechanism that enforces atomicity
 - Semantics:
 - » Lock(L): If L is not currently locked \rightarrow atomically lock it
 - If L is currently locked \rightarrow block until it becomes free
 - » Unlock(L): Release control of L
 - You can use a lock to protect data: Lock(L) before accessing data, Unlock(L) when done

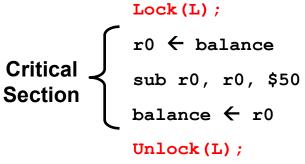


Fixing the ATM problem

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Problem:	<u>SALLY</u>
 Balance update not atomic 	Lock(L);
• Solution:	r0 🗲 balance
 Introduce atomic operations 	add r0, r0, \$50
• Effect:	balance 🗲 r0
+ Eliminates race condition	Unlock(L);
 Increases overhead 	
 Restricts concurrency 	Lock (L
Open issues:	$\int r0 \leftarrow h$

- Where do we use locks?
 - » Avoid deadlocks or livelocks
 - » Ensure fairness
- How do we implement locks?
- What other synch ops are there besides locks?



BOB

Lock Requirements

- 1. Must guarantee that only one process / thread is in the critical section at a time
 - This is obvious
- 2. Must guarantee progress
 - Processes or threads don't have to wait for an available lock
- **3.** Must guarantee bounded waiting
 - No process or thread needs to wait forever to enter the critical section
 - Figuring out the bound can be interesting



Goal:

- If milk needed, somebody buys
- Only one person buys milk
- Idea: Wait while note is up
 "Busy wait" loop
- Does this work?
 - Is milk bought?
 - Can both buy?

FAILS: Can <u>both</u> buy milk (How?)

<u>P0</u>:

while (Note) { }
Note < 1; // leave Note
Milk < Milk + 1; // CritSect
Note < 0; // remove Note</pre>

<u>P1</u>:

while (Note) { }
Note < 1; // leave Note
Milk < Milk + 1; // CritSect
Note < 0; // remove Note</pre>





Goal:

- If milk needed, somebody buys
- Only one person buys milk
- Idea: Add per-process flag
 - Set flag while in critical section
 - Explicit check on other process
- Does this work?
 - Is milk bought?
 - Can both buy?

FAILS: Can <u>both</u> buy milk (How?) $flag[2] = \{0, 0\};$

<u>P0</u>:

```
while (flag[1]) { }
flag[0] < 1;
Milk < Milk + 1; // Crit sect
flag[0] < 0;</pre>
```

<u>P1</u>:





Goal:

- If milk needed, somebody buys
- Only one person buys milk
- Reverse order in which you set and test flag
 - Set flag before testing this time
- Does this work?
 - Is milk bought?
 - Can both buy?

FAILS: Violates progress and bounded wait

 $flag[2] = \{0, 0\};$

P0:
flag[0] ← 1;
while (flag[1]) { }
Milk ← Milk + 1; // Crit sect
flag[0] ← 0;;

P1: flag[1] \leftarrow 1; while (flag[0]) { } Milk \leftarrow Milk + 1; // Crit sect flag[1] \leftarrow 0;





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• Goal:

- If milk needed, somebody buys
- Only one person buys milk
- Idea: Alternating turns
 - Let one in at a time
 - Wait your turn
- Does this work?
 - Is milk bought?
 - Can both buy?

FAILS: Violates progress and bounded waiting

turn \leftarrow 0;

<u>P0</u>:

<u>P1</u>:

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Lecture 7

• Goal:

- If milk needed, somebody buys
- Only one person buys milk
- Idea: Combine approaches
 - Use flag[] to denote interest
 - Use turn to break ties
- Does this work?
 - Is milk bought?
 - Can both buy?

SUCCEEDS: Meets all three criteria for locks flag[2] ← {0,0}; turn ← 0;
P0:

flag[0] ← 1; turn ← 1; while (flag[1] && turn == 1) { } Milk ← Milk + 1; // Crit sect flag[0] ← 0;

<u>P1</u>:

```
flag[1] \leftarrow 1; turn \leftarrow 0;
while (flag[0] && turn == 0) { }
Milk \leftarrow Milk + 1; // Crit sect
flag[1] \leftarrow 0;
```



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Milk V.5

Peterson's Algorithm

- Algorithm on previous slide was published by Peterson in 1981
 - Should work on any uniprocessor
 - » Relies only on atomicity of memory operations
 - Can be extended to more than 2 threads

Peterson's algorithm does not work on any modern multicore machine

- It depends on certain guarantees provided by the memory subsystem, such as not reordering stores
- Fixing the algorithm is not totally trivial
- These fixes are not portable to other architectures



Lock Correctness

How do I show that a lock implementation is wrong?

How do I argue that a lock implementation is right?





- Critical sections are those that must execute atomically
 - Locks are a way to get atomicity
 - Locks are implemented using lower-level atomic operations
- Locks should guarantee mutual exclusion, progress, and bounded waiting
- Implementing locks is tricky
 - Many published solutions have been wrong for years before somebody noticed the problem
 - Even harder on a modern machine
- In real life, 99.9% of the time you don't implement synchronization operations yourself





